

FIG. 1

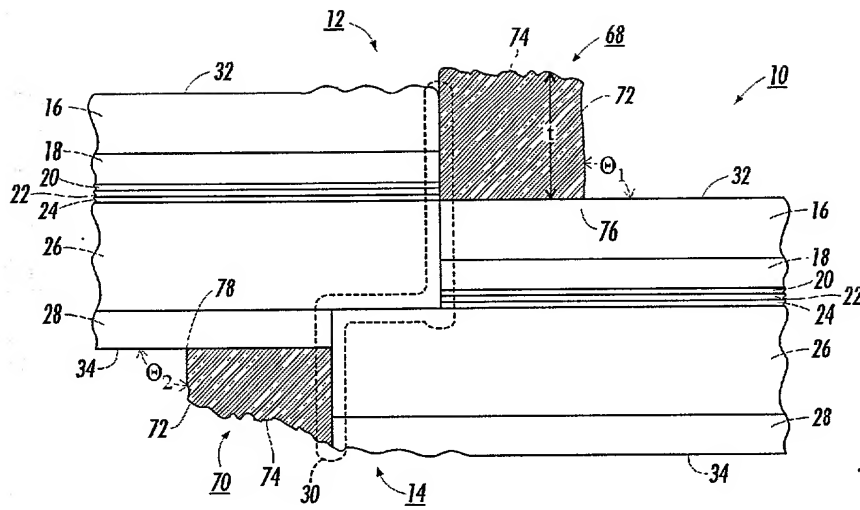


FIG. 2

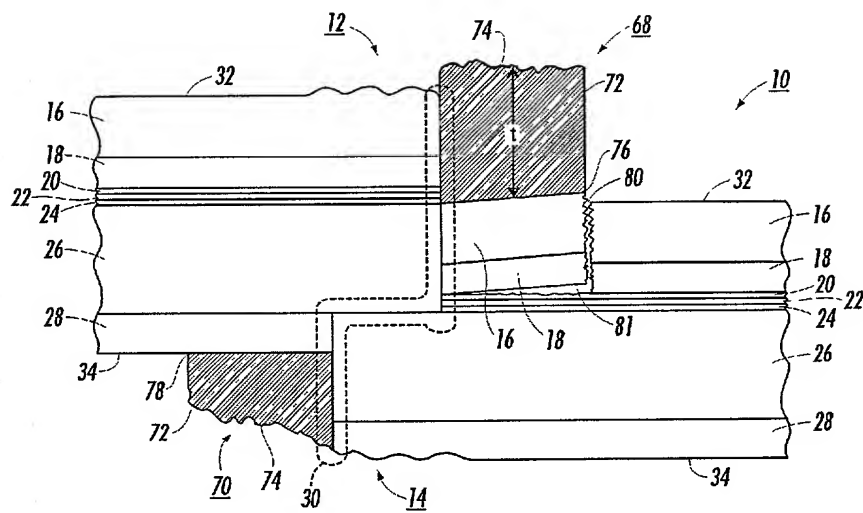


FIG. 3

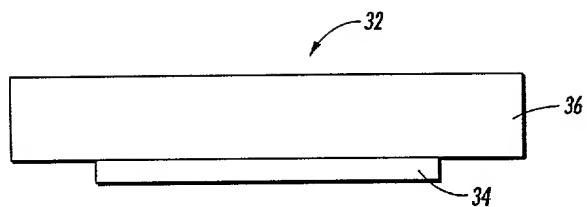


FIG. 4

1. A method of determining a position of a vehicle, comprising:
 2. receiving a signal from a first sensor;
 3. receiving a signal from a second sensor;
 4. determining a position of the vehicle based on the signals;
 5. outputting the position of the vehicle.

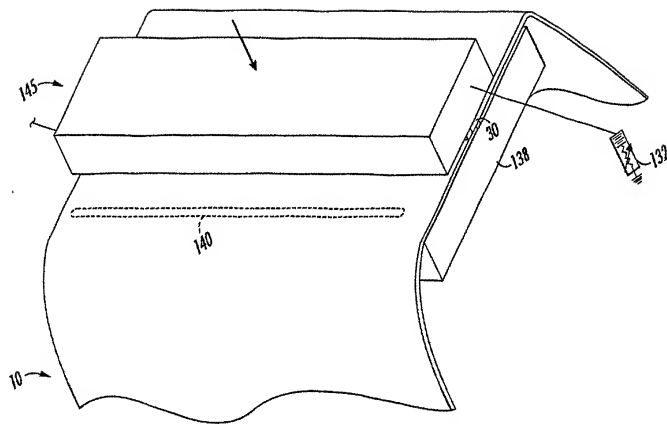


FIG. 5

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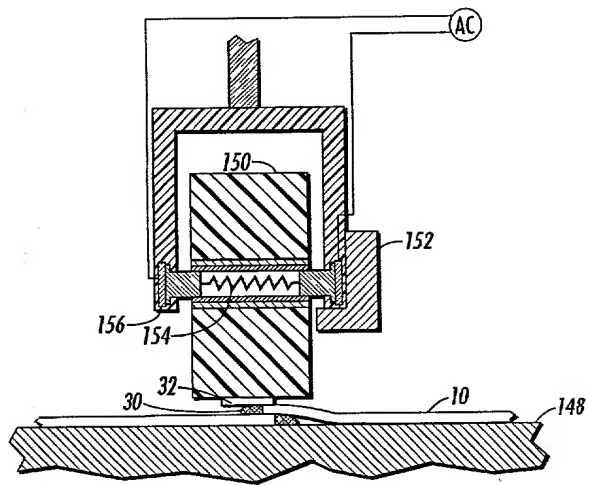


FIG. 6

FIG. 6 is a cross-sectional view of the device 100 in a first state. The device 100 includes a base 10, a first layer 30, a second layer 32, a third layer 150, a fourth layer 152, a fifth layer 154, a sixth layer 156, and a seventh layer 158. The device 100 is configured to be used in a first state and a second state. In the first state, the device 100 is configured to be used in a first state. In the second state, the device 100 is configured to be used in a second state.

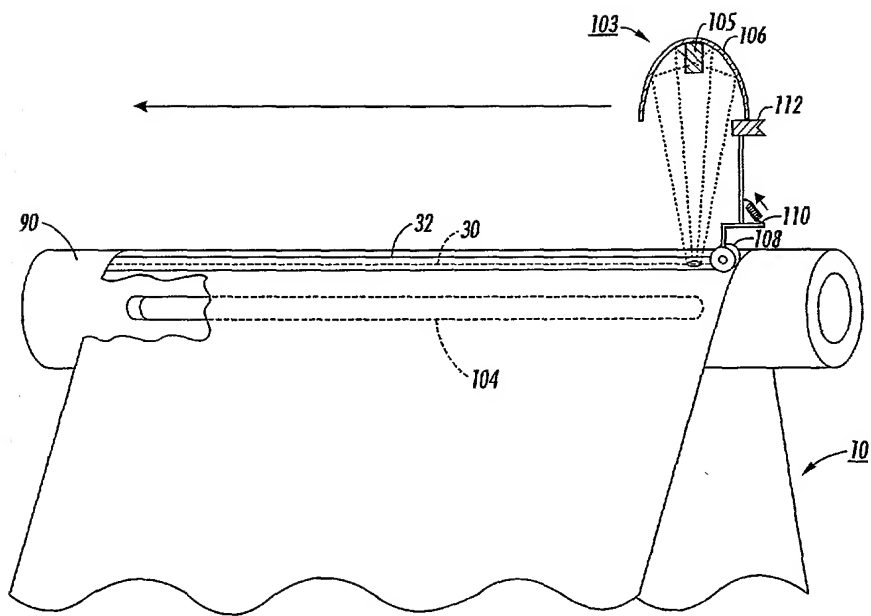


FIG. 7

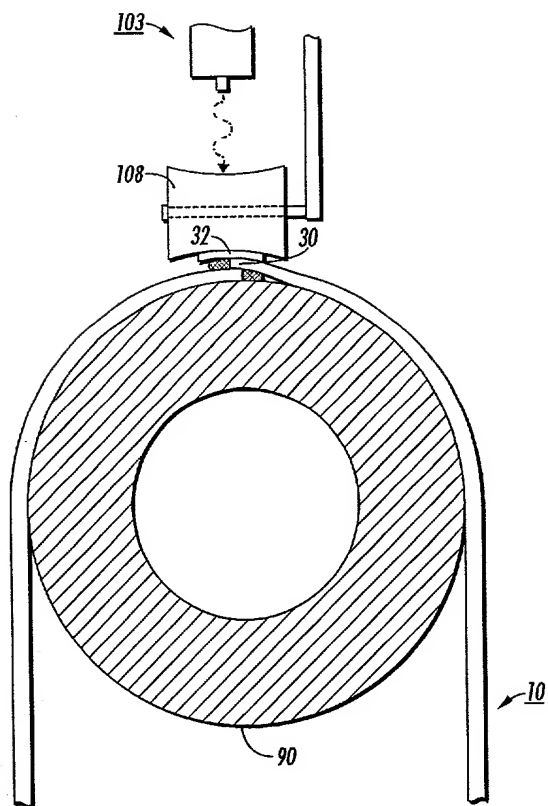


FIG. 8

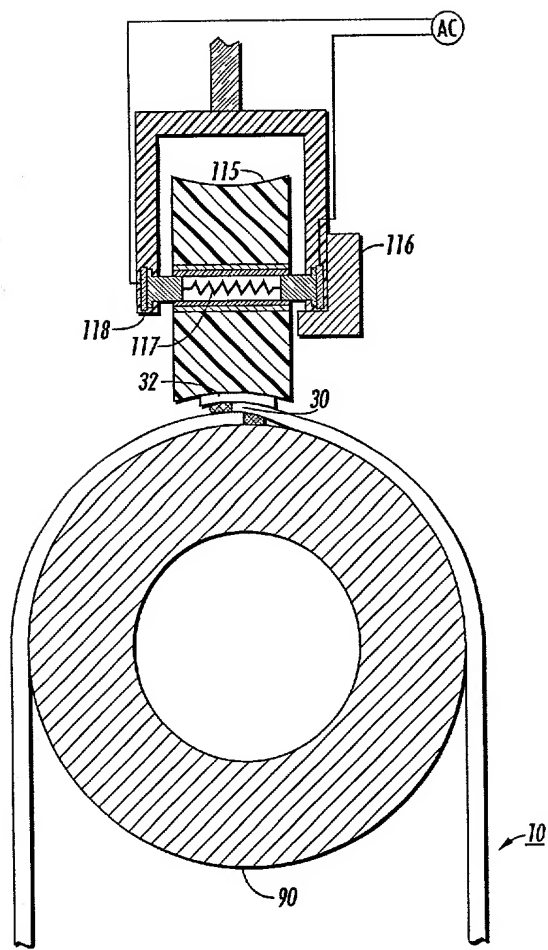


FIG. 9